# Mixed graph searching games are all monotone 

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Joint work with
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## Back to the roots - Let us revisit mixed search games



## Mixed search game



The fugitive is located on an edge

A play of a mixed search game is a sequence

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\mathcal{P}=\left\langle\emptyset, a_{4} b_{4}, \ldots\right\rangle
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$\rightsquigarrow$ The fugitive is captured if it cannot escape its location: the two vertices incident to its location are occupied by searchers.

## Known results on (node/mixed) search games (1/3)

$\rightsquigarrow$ width parameters

[Ellis, Subdbourough, Turner'94]

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$\rightsquigarrow$ width parameters

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ctp - Cartesian Tree Product number [Harvey'14]; also known as
la - Largeur arborescente [Colin de Verdière'98]

## Known results on (node/mixed) search games (2/3)

$\rightsquigarrow$ monotonicity (recontamination does not help the capture)
[Dendris, Kirousis, Thilikos'97]

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## Known results on (node/mixed) search games (3/3)

$\rightsquigarrow$ obstacle / certificate


## Our result

## Theorem:

Let $G$ be a graph and $k \in \mathbb{N}$. Then the following conditions are equivalent:

1. $G$ has a loose tree-decomposition of width $k$;
2. $\operatorname{ctp}(G) \leq k \rightsquigarrow G$ is a minor of $T^{(k)}=T \square K_{k}$;
3. every tight bramble of $G$ has order at most $k$;
4. $\operatorname{avms}(G) \leq k \rightsquigarrow$ the mixed search number against an agile and visible fugitive is at most $k$;
5. $\operatorname{mavms}(G) \leq k \rightsquigarrow$ the monotone mixed search number against an agile and visible fugitive is at most $k$.

## Mixed search strategy (against a visible fugitive)

A mixed search strategy is a function

$$
\mathbf{s}_{G}: 2^{V(G)} \times E(G) \rightarrow 2^{V(G)}
$$

st. $\forall(S, e) \in 2^{V(G)} \times E(G),\left(S, \mathbf{s}_{G}(S, e)\right)$ is a legitimate searchers' move:
$\rightsquigarrow$ [Placement of a searcher]: $\mathbf{s}_{G}(S, e)=S \cup\{x\} ;$
$\rightsquigarrow\left[\right.$ Removal of a searcher]: $\mathbf{s}_{G}(S, e)=S \backslash\{x\}$;
$\rightsquigarrow$ [Sliding on an edge]: $\mathbf{s}_{G}(S, e) \ominus S=\{x, y\}$ and $x y \in E(G)$.

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A legitimate searchers' move $\left(S, S^{\prime}\right)$ clears the following set of edges:

$$
\operatorname{Clear}_{G}\left(S, S^{\prime}\right)=\left\{\begin{array}{cl}
\{x y \mid y \in S\} \cap E(G), & \text { if } S^{\prime} \backslash S=\{x\} \\
\emptyset, & \text { if } S^{\prime} \backslash S=\emptyset
\end{array}\right.
$$

## The (agile) fugitive strategy (1/2)



The set of accessible edges of $G$ from $e$ is:
$\operatorname{Acc}_{G}\left(S, e, S^{\prime}\right)=\left\{\left.e^{\prime} \in E(G) \backslash\binom{S^{\prime}}{2} \right\rvert\, \exists\right.$ an $\left(S, S^{\prime}\right)$-avoiding $\left(e, e^{\prime}\right)$-pathway $\}$.

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The fugitive space is:

$$
\operatorname{freeSp}_{G}\left(S, e, S^{\prime}\right)=\left(\{e\} \backslash \operatorname{Clear}_{G}\left(S, S^{\prime}\right)\right) \cup \operatorname{Acc}_{G}\left(S, e, S^{\prime}\right) .
$$

## Search program and mixed search number

A fugitive strategy on $G$ is a pair $\left(e_{1}, \mathbf{f}_{G}\right)$ with $e_{1} \in E(G)$ and

$$
\mathbf{f}_{G}: 2^{V(G)} \times E(G) \times 2^{V(G)} \rightarrow E \cup\{\star\} .
$$

and such that

- if free $S_{G}\left(S, e, S^{\prime}\right) \neq \emptyset$, then $\mathbf{f}_{G}\left(S, e, S^{\prime}\right) \in \operatorname{free} \mathrm{Pp}_{G}\left(S, e, S^{\prime}\right)$
- otherwise $\mathrm{f}_{G}\left(S, e, S^{\prime}\right)=\star \quad$ (the fugitive is captured).


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A search program on $G$ is a pair $\left(\mathbf{s}_{G},\left(e_{1}, \mathbf{f}_{G}\right)\right)$ generating a play:

$$
\mathcal{P}\left(\mathbf{s}_{G}, e_{1}, \mathbf{f}_{G}\right)=\left\langle S_{0}, e_{1}, S_{1}, \ldots, S_{i-1}, e_{i}, S_{i}, e_{i+1}, \ldots\right\rangle
$$

where for each $i \geq 1$,

- $S_{i}=\mathbf{s}_{G}\left(S_{i-1}, e_{i-1}\right)$ and
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The cost of a search program is:

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$\rightsquigarrow$ The mixed search number (against an agile and visible fugitive) is:
$\operatorname{avms}(G)=\min _{\mathbf{s}_{G} \text { winning }} \max \left\{\boldsymbol{\operatorname { c o s t }}\left(\mathcal{P}\left(\mathbf{s}_{G}, e_{1}, \mathbf{f}_{G}\right)\right) \mid\left(e_{1}, \mathbf{f}_{G}\right)\right.$ is a fugitive strategy $\}$.

## Monotone search program

$\rightsquigarrow$ The search program ( $\mathbf{s}_{G}, e_{1}, \mathbf{f}_{G}$ ) is monotone if, in $\mathcal{P}\left(\mathbf{s}_{G}, e_{1}, \mathbf{f}_{G}\right)$, for every $i \geq 1$, the edge $e_{i+1}$ has not been cleared at any step prior to $i$, that is:

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$\rightsquigarrow$ The monotone mixed search number is:
$\operatorname{mavms}(G)=\min \left\{\boldsymbol{\operatorname { c o s t }}\left(\mathbf{s}_{G}\right) \mid \mathbf{s}_{G}\right.$ is a monotone winning search strategy $\}$.

## Our result

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Let $G$ be a graph and $k \in \mathbb{N}$. Then the following conditions are equivalent:

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## Loose tree-decomposition

A loose tree-decomposition is a pair $\mathcal{D}=(T, \chi)$ such that $T$ is a tree and $\chi: V(T) \rightarrow 2^{V(G)}$ satisfying the following properties:
(L1) $\forall x \in V(G), T_{x}=\{t \in V(T) \mid x \in \chi(t)\}$ is non-empty and connected in $T$.


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(L3) $\forall\left\{t_{1}, t_{2}\right\} \in E(T)$,

$$
\left|E\left(G\left[\chi\left(t_{1}\right) \cup \chi\left(t_{2}\right)\right]\right) \backslash\left(E\left(G\left[\chi\left(t_{1}\right)\right]\right) \cup E\left(G\left[\chi\left(t_{2}\right)\right]\right)\right)\right| \leq 1 .
$$



## Cartesian tree product number


$T$


Definition [Harvey'14, Colin De Verdière'98]
The cartesian tree product number of a graph $G$ is

$$
\operatorname{ctp}(G)=\min \left\{k \in \mathbb{N} \mid G \text { is a minor of } T^{(k)}\right\} .
$$

## Cartesian tree product number

Theorem

$$
\operatorname{ctp}(G)=\min \{\operatorname{width}(\mathcal{D}, G) \mid \mathcal{D} \text { is a loose tree-decomposition of } G\} .
$$



## Tight bramble

Two subsets $S_{1}$ and $S_{2}$ of $V(G)$ are tightly touching if
$\rightsquigarrow$ either $S_{1} \cap S_{2} \neq \emptyset$
$\rightsquigarrow$ or $E(G)$ contains two distinct edges $x_{1} x_{2}$ and $y_{1} y_{2}$ such that $x_{1}, y_{1} \in S_{1}$ and $x_{2}, y_{2} \in S_{2}$.

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A set $S \subseteq V(G)$ is a cover of $\mathcal{B}$ if for every set $B \in \mathcal{B}, S \cap B \neq \emptyset$. The order of the bramble $\mathcal{B}$ is the smallest size of a cover of $\mathcal{B}$.

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Theorem
$\operatorname{ctp}(G) \leq k$ if and only if every tight bramble of $G$ has order at most $k$.

## Escape strategy derived from a tight bramble

Theorem: If $G$ has a tight bramble $\mathcal{B}$ of order $k$, then $\operatorname{avms}(G) \geq k$.
Suppose that a searcher slides on the edge $u v$ and that

$$
\mathcal{P}\left(\mathbf{s}_{G}, e_{1}, \mathbf{f}_{G}\right)=\left\langle\emptyset, e_{1}, \ldots S_{i-1}, e_{i}, S_{i}, e_{i+1} \ldots\right\rangle
$$

$\rightsquigarrow$ there exists a pathway from $e_{i}$ to $e_{i+1}$ going through the edge $x y$ that avoids the edge $u v$.

Monotone search strategy derived from a loose tree-decomposition

Theorem: If $\boldsymbol{\operatorname { c t p }}(G) \leq k$, then $\operatorname{mavms}(G) \leq k$.

$$
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Thank you !

