

THE COMPLEXITY OF COMPUTING OPTIMUM LABELINGS FOR TEMPORAL CONNECTIVITY

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Width Parameters (GROW)

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TEMPORAL GRAPHS

Definition

A temporal graph \mathcal{G} is a pair (G, λ) where:

- ▶ $G = (V, E)$ is an underlying (di)graph and
- ▶ $\lambda : E \rightarrow 2^{\mathbb{N}}$ is a discrete time-labeling function.

Maximum label is called a *lifetime (age)* of \mathcal{G} .

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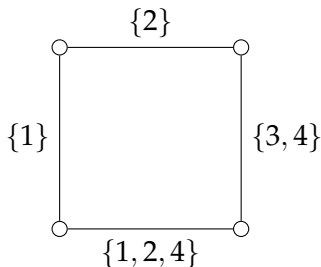
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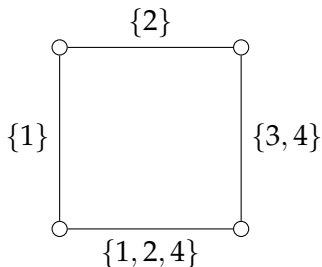
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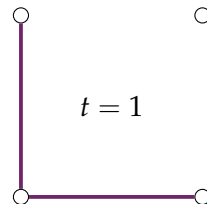
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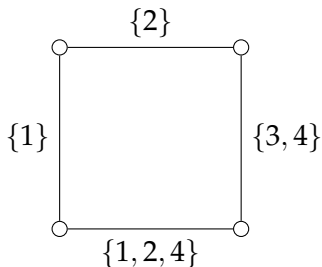
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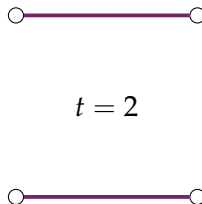
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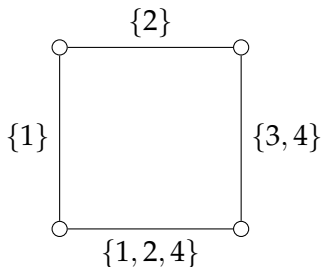
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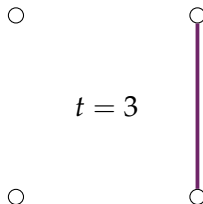
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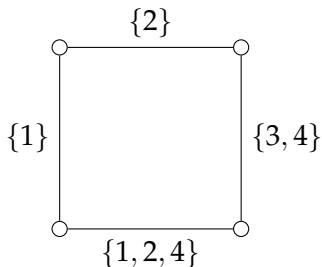
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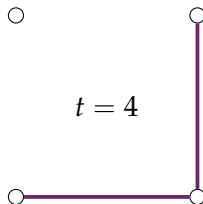
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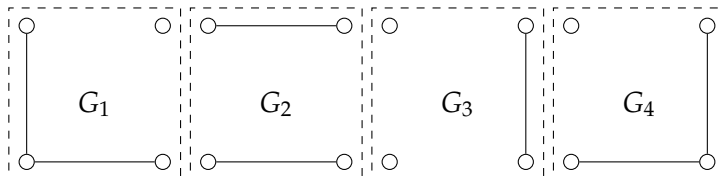
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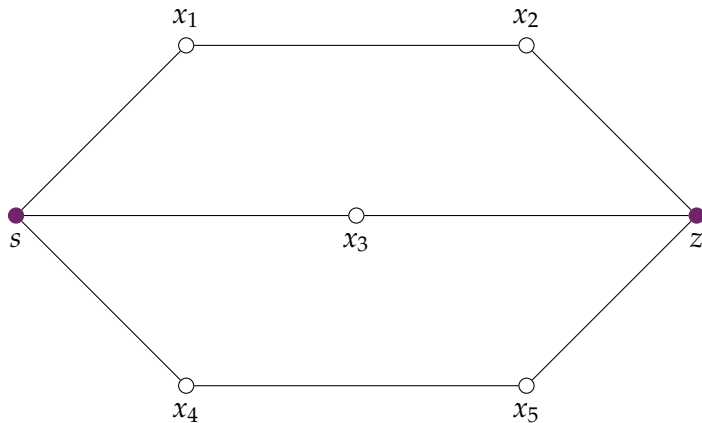
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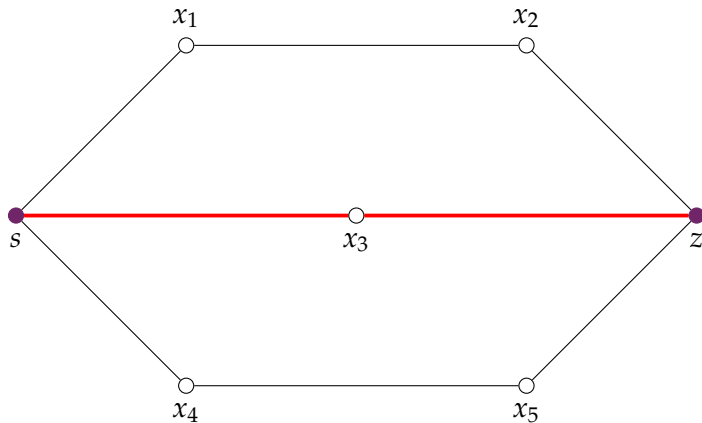
Alternatively we can view it as a sequence of static graphs, called *snapshots*:



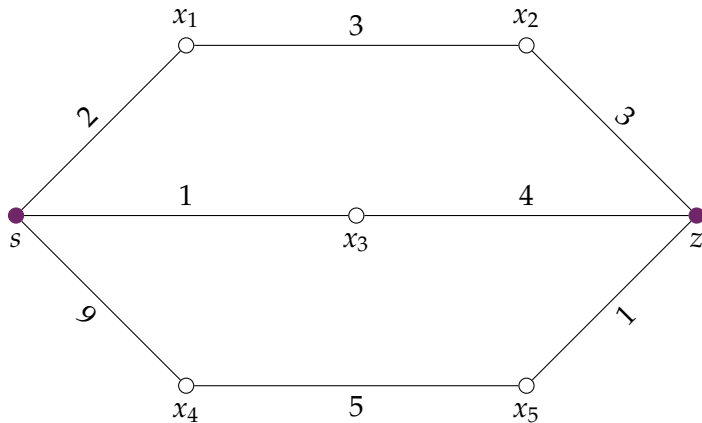
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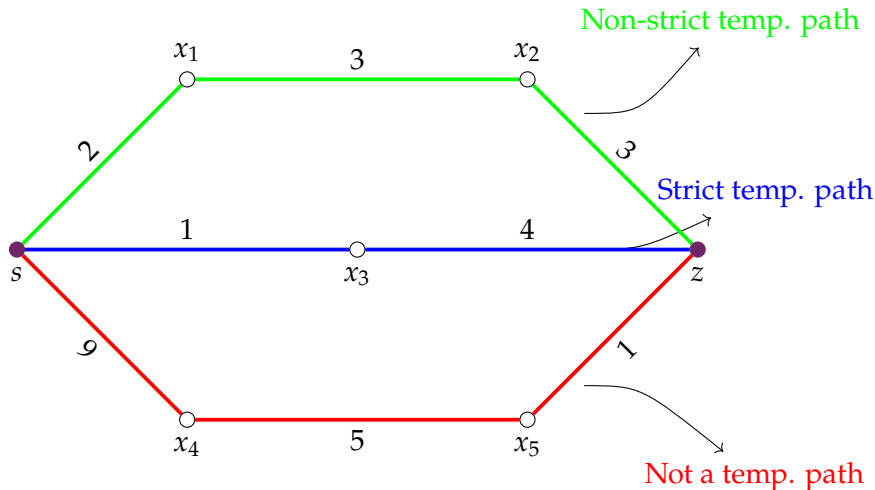
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A temporal graph \mathcal{G} is (temporally) connected iff for all $u, v \in V(G)$ there exists a temporal (u, v) -path¹.

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- ▶ Maximum label $\alpha(\lambda)$ is called the **age** of \mathcal{G} .
- ▶ The total **cost** of (G, λ) is $|\lambda| = \sum_{e \in E} |\lambda_e|$.

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PROBLEM(S) DEFINITIONS I

Min. Labeling (ML)

Input: A static graph $G = (V, E)$ and an integer $k \in \mathbb{N}$.

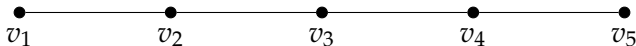
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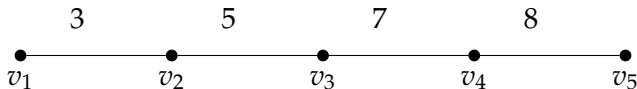


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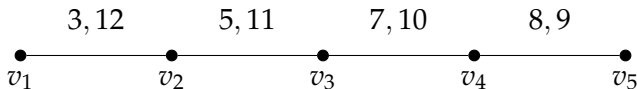


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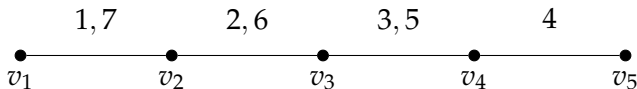


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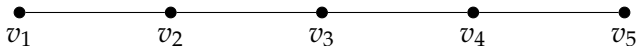
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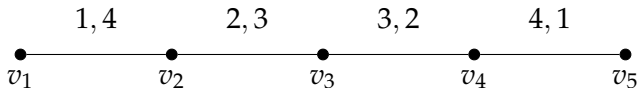
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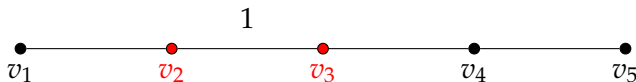


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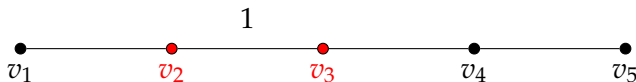
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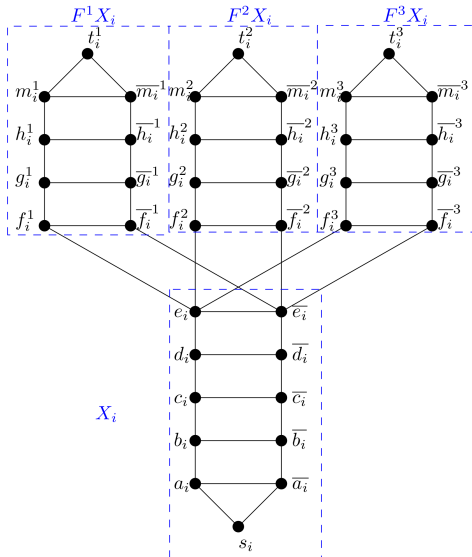
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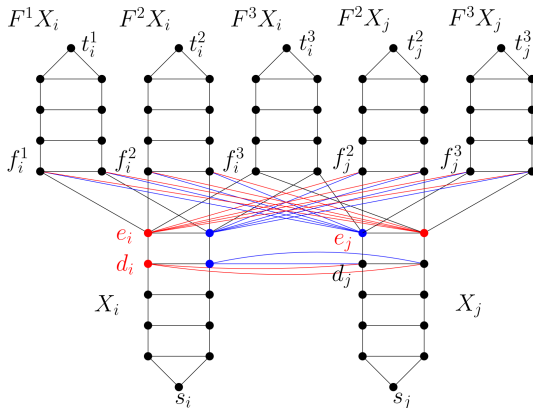
- conjunction of XOR clauses,
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- variables appear exactly 3 times.

VARIABLE GADGETS



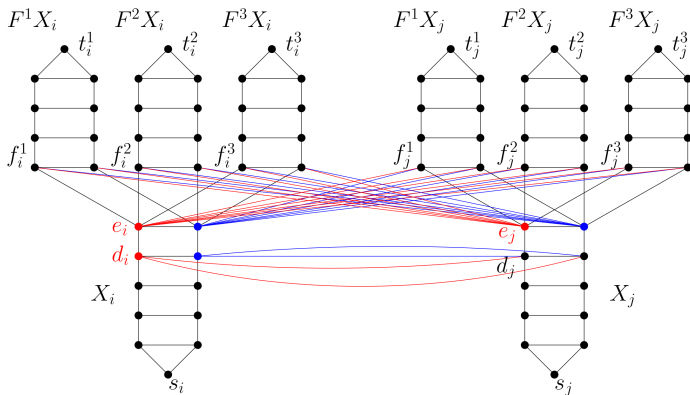
CONNECTING VARIABLE GADGETS I

Clause $(x_i \oplus x_j)$ with 3rd and 1st appearance of x_i, x_j , respectively.



CONNECTING VARIABLE GADGETS II

No clause with x_i and x_j .



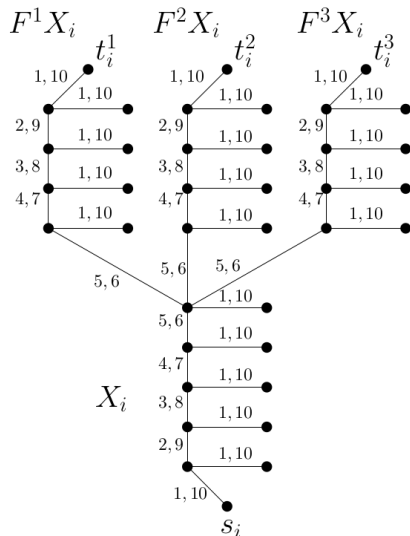
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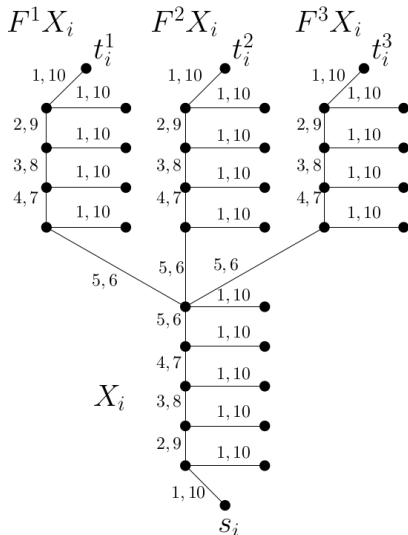
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$$OPT(G_\phi, d_\phi) \leq \text{poly}(n, k)$$

$$\Leftrightarrow$$

$$OPT(\phi) \geq k.$$



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Idea of the algorithm:

- ▶ Use an FPT algorithm for Steiner Tree.
- ▶ Iterate over all C_4 s in G , check if one can be labeled in an optimum solution.

Thank you!

Questions?

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- ▶ What if we require two temporally disjoint paths among vertices?