# On Structural Parameterizations of Continuous Facility Location Problems on Graphs 

Stefan Lendl<br>Institute of Operations and Information Systems<br>University of Graz


joint work with Tim A. Hartmann

GROW 2022

## Continuous Facility Location on Graphs



- Graph $G=(V, E)$, connected, unit length


## Continuous Facility Location on Graphs



- Graph $G=(V, E)$, connected, unit length
- $P(G)$ continuum set of points on edges and vertices


## Continuous Facility Location on Graphs



- Graph $G=(V, E)$, connected, unit length
- $P(G)$ continuum set of points on edges and vertices
- $d(p, q)$ shortest distance between $p$ and $q$


## $\delta$-Dispersion and $\delta$-Covering Number



- $S \subset P(G) \delta$-dispersed: $\forall p \neq q \in S: d(p, q) \geq \delta$

$$
\delta \text {-disp }(G)=\max \{|S|: S \subset P(G), S \delta \text {-dispersed }\}
$$

## $\delta$-Dispersion and $\delta$-Covering Number



- $S \subset P(G) \delta$-dispersed: $\forall p \neq q \in S: d(p, q) \geq \delta$

$$
\delta \text {-disp }(G)=\max \{|S|: S \subset P(G), S \delta \text {-dispersed }\}
$$

- $S \subset P(G) \delta$-covering: $\forall p \in P(G) \exists s \in S: d(p, s) \leq \delta$

$$
\delta-\operatorname{cov}(G)=\min \{|S|: S \subset P(G), S \delta \text {-covering }\}
$$

## Computational Complexity of $\delta$-Dispersion

[Grigiorev, Hartmann, L. Woeginger, STACS 2019]
Complete picture of computational complexity for rational $\delta$ :

## Computational Complexity of $\delta$-Dispersion

[Grigiorev, Hartmann, L. Woeginger, STACS 2019]
Complete picture of computational complexity for rational $\delta$ :

- $\delta=\frac{1}{b}$ :

$$
\frac{1}{b}-\operatorname{disp}(G)= \begin{cases}b|E|+1 & G \text { is a tree } \\ b|E| & \text { else }\end{cases}
$$

## Computational Complexity of $\delta$-Dispersion

[Grigiorev, Hartmann, L. Woeginger, STACS 2019]
Complete picture of computational complexity for rational $\delta$ :

- $\delta=\frac{1}{b}$ :

$$
\frac{1}{b}-\operatorname{disp}(G)= \begin{cases}b|E|+1 & G \text { is a tree } \\ b|E| & \text { else }\end{cases}
$$

- $\delta=\frac{a}{b}, a \geq 3, \operatorname{gcd}(a, b)=1$ : NP-hard
- Independent set in cubic graphs
- Lemma of Bézout


## Computational Complexity of $\delta$-Dispersion

[Grigiorev, Hartmann, L. Woeginger, STACS 2019]
Complete picture of computational complexity for rational $\delta$ :

- $\delta=\frac{1}{b}$ :

$$
\frac{1}{b}-\operatorname{disp}(G)= \begin{cases}b|E|+1 & G \text { is a tree } \\ b|E| & \text { else }\end{cases}
$$

- $\delta=\frac{2}{b}$ : polynomial time algorithm
- Matchings (Edmonds-Gallai decomposition)
- Submodular optimization (directed $s$ - $t$-cut)
- $\delta=\frac{a}{b}, a \geq 3, \operatorname{gcd}(a, b)=1$ : NP-hard
- Independent set in cubic graphs
- Lemma of Bézout


## Computational Complexity of $\delta$-Dispersion

[Grigiorev, Hartmann, L. Woeginger, STACS 2019]
Complete picture of computational complexity for rational $\delta$ :

- $\delta=\frac{1}{b}$ :

$$
\frac{1}{b}-\operatorname{disp}(G)= \begin{cases}b|E|+1 & G \text { is a tree } \\ b|E| & \text { else }\end{cases}
$$

- $\delta=\frac{2}{b}$ : polynomial time algorithm
- Matchings (Edmonds-Gallai decomposition)
- Submodular optimization (directed $s$ - $t$-cut)
- $\delta=\frac{a}{b}, a \geq 3, \operatorname{gcd}(a, b)=1$ : NP-hard
- Independent set in cubic graphs
- Lemma of Bézout
[Hartmann, L. Woeginger, IPCO 2020] Similar results for $\delta$-covering


## Influence of Structural Graph Parameters?

## Studied structural parameters:

PART I: Parameters leading to sparse graphs:

- treewidth $\mathrm{tw}(G)$
- pathwidth pw(G)
- size of a feedback vertex set fvs $(G)$
- treedepth $\operatorname{td}(G)$

PART II: Structural parameterizations of dense graphs:

- neighborhood diversity nd( $G$ )


## Overview of results

[Hartmann, L.; MFCS 2022] Main ingredients:

- Connection to distance- $d$ independent set
- L length of longest path in $G$ and rounding $\delta$


## Overview of results

[Hartmann, L.; MFCS 2022] Main ingredients:

- Connection to distance- $d$ independent set
- L length of longest path in $G$ and rounding $\delta$
treewidth $\mathrm{tw}(G)$
- XP with running time $(2 L)^{\operatorname{tw}(G)} n^{\mathcal{O}(1)}$
- no $n^{o(\operatorname{tw}(G)+\sqrt{k})}$, assuming ETH
pathwidth $\mathrm{pw}(G)$, size of a feedback vertex set fvs $(G)$
- W[1]-hard even for the combined parameter $\mathrm{pw}(G)+k$
- W[1]-hard for fvs( $G$ )
treedepth $\operatorname{td}(G)$
- FPT with running time $2^{\mathcal{O}\left(\operatorname{td}(G)^{2}\right)} n^{\mathcal{O}(1)}$
- no $2^{o\left(\operatorname{td}(G)^{2}\right)}$ algorithm, assuming ETH


## Dispersion and Independent Set

$\alpha_{d}(G)$ maximum size of a distance- $d$ independent set

## Lemma

Consider integers $a, b$ and a $2 b$-subdivision $G_{2 b}$ of a graph $G$. Then $\frac{a}{b}$-disp $(G)=\alpha_{2 a}\left(G_{2 b}\right)$.


## Dispersion and Independent Set

$\alpha_{d}(G)$ maximum size of a distance- $d$ independent set

## Lemma

Consider integers $a, b$ and a $2 b$-subdivision $G_{2 b}$ of a graph $G$. Then $\frac{a}{b}$-disp $(G)=\alpha_{2 a}\left(G_{2 b}\right)$.


## Dispersion and Independent Set

$\alpha_{d}(G)$ maximum size of a distance- $d$ independent set

## Lemma

Consider integers $a, b$ and $a b$-subdivision $G_{2 b}$ of a graph $G$. Then $\frac{a}{b}$-disp $(G)=\alpha_{2 a}\left(G_{2 b}\right)$.


Using [Katsikarelis, Lampis, Paschos; DAM 2022] we get

## Theorem

$\frac{a}{b}-\operatorname{disp}(G)$ can be computed in time $(2 a)^{\operatorname{tw}(G)}(b n)^{\mathcal{O}(1)}$.

## Translating $\delta$-Dispersion

## Lemma

For $\delta \in(0,3]$ we have $\delta-\operatorname{disp}(G)=\frac{\delta}{\delta+1}-\operatorname{disp}(G)+|E(G)|$.

## Translating $\delta$-Dispersion

## Lemma

For $\delta \in(0,3]$ we have $\delta-\operatorname{disp}(G)=\frac{\delta}{\delta+1}-\operatorname{disp}(G)+|E(G)|$.

Problem for $\delta>3$ : locally-injective $p$ to $p$ walk.

$$
\delta=3+\varepsilon \Rightarrow \frac{\delta}{\delta+1}>\frac{3}{4}
$$



## Rounding the Distance

Observation: For given $G$ and $\delta$ there might exist $\delta^{\star}>\delta$ such that $\delta$-disp $(G)=\delta^{\star}$-disp $(G)$.

## Rounding the Distance

Observation: For given $G$ and $\delta$ there might exist $\delta^{\star}>\delta$ such that $\delta$-disp $(G)=\delta^{\star}$-disp $(G)$. Question: Can we state some properties of $\delta^{\star}$ ?

## Rounding the Distance

Observation: For given $G$ and $\delta$ there might exist $\delta^{\star}>\delta$ such that $\delta$-disp $(G)=\delta^{\star}$-disp $(G)$. Question: Can we state some properties of $\delta^{\star}$ ?

Illustrative example: $P_{6}$

$$
\delta=\frac{15}{11}
$$

## Rounding the Distance

Observation: For given $G$ and $\delta$ there might exist $\delta^{\star}>\delta$ such that $\delta$-disp $(G)=\delta^{\star}$-disp $(G)$. Question: Can we state some properties of $\delta^{\star}$ ?

Illustrative example: $P_{6}$

$$
\delta=\frac{3}{4}
$$

## Rounding the Distance

Observation: For given $G$ and $\delta$ there might exist $\delta^{\star}>\delta$ such that $\delta$-disp $(G)=\delta^{\star}$-disp $(G)$. Question: Can we state some properties of $\delta^{\star}$ ?

Illustrative example: $P_{6}$

$$
\delta=\frac{3}{4}
$$


$\delta^{*}$ depends on $L$, the length of the longest (non-induced) path in $G$

## Rounding the Distance

## Theorem

Let $\delta \in \mathbb{R}^{+}$. Let $L$ be an upper bound on the length of paths in $G$. Let $\delta^{\star}=\frac{a^{\star}}{b^{\star}} \geq \delta$ minimal with $a^{\star} \leq 2 L$ and $b^{\star} \in \mathbb{N}$. Then $\delta-\operatorname{disp}(G)=\delta^{\star}-\operatorname{disp}(G)$.

## Rounding the Distance

## Theorem

Let $\delta \in \mathbb{R}^{+}$. Let $L$ be an upper bound on the length of paths in $G$. Let $\delta^{\star}=\frac{a^{\star}}{b^{\star}} \geq \delta$ minimal with $a^{\star} \leq 2 L$ and $b^{\star} \in \mathbb{N}$. Then $\delta-\operatorname{disp}(G)=\delta^{\star}-\operatorname{disp}(G)$.

Observation: Inverse of $\delta^{\star}$ is the next smaller rational number of the inverse of $\delta$ in the Farey sequence of order $2 L$.

## Rounding the Distance

## Theorem

Let $\delta \in \mathbb{R}^{+}$. Let $L$ be an upper bound on the length of paths in $G$. Let $\delta^{\star}=\frac{a^{\star}}{b^{\star}} \geq \delta$ minimal with $a^{\star} \leq 2 L$ and $b^{\star} \in \mathbb{N}$. Then $\delta-\operatorname{disp}(G)=\delta^{\star}-\operatorname{disp}(G)$.

Observation: Inverse of $\delta^{\star}$ is the next smaller rational number of the inverse of $\delta$ in the Farey sequence of order $2 L$.

Main idea: Push points of $\delta$-dispersed set $S$ away from each other such that the new set is $(\delta+\epsilon)$-dispersed.
During pushing certain events occur or we reach $\delta^{\star}$.

## Rounding the Distance

## Theorem

Let $\delta \in \mathbb{R}^{+}$. Let $L$ be an upper bound on the length of paths in $G$. Let $\delta^{\star}=\frac{a^{\star}}{b^{\star}} \geq \delta$ minimal with $a^{\star} \leq 2 L$ and $b^{\star} \in \mathbb{N}$. Then $\delta-\operatorname{disp}(G)=\delta^{\star}-\operatorname{disp}(G)$.

Observation: Inverse of $\delta^{\star}$ is the next smaller rational number of the inverse of $\delta$ in the Farey sequence of order $2 L$.

Main idea: Push points of $\delta$-dispersed set $S$ away from each other such that the new set is $(\delta+\epsilon)$-dispersed.
During pushing certain events occur or we reach $\delta^{\star}$.
A pair of points $\{p, q\}$ is $\delta$-critical, if they have distance exactly $\delta$. These points we push!

## Rounding the Distance

## Theorem

Let $\delta \in \mathbb{R}^{+}$. Let $L$ be an upper bound on the length of paths in $G$. Let $\delta^{\star}=\frac{a^{\star}}{b^{\star}} \geq \delta$ minimal with $a^{\star} \leq 2 L$ and $b^{\star} \in \mathbb{N}$. Then $\delta-\operatorname{disp}(G)=\delta^{\star}-\operatorname{disp}(G)$.

Observation: Inverse of $\delta^{\star}$ is the next smaller rational number of the inverse of $\delta$ in the Farey sequence of order $2 L$.

Main idea: Push points of $\delta$-dispersed set $S$ away from each other such that the new set is $(\delta+\epsilon)$-dispersed.
During pushing certain events occur or we reach $\delta^{\star}$.
A pair of points $\{p, q\}$ is $\delta$-critical, if they have distance exactly $\delta$. These points we push!
(Event 1) A $\delta$-uncritical pair of points $\{p, q\}$ becomes $(\delta+\varepsilon)$-critical.

## Coordination of Movement

Consider a sequence of point $p_{0}, p_{1}, p_{2}, \ldots$ with $\left\{p_{i}, p_{i+1}\right\}$ critical.
Move $p_{0}$ by $0, p_{1}$ by $\varepsilon, p_{2}$ by $2 \varepsilon, \ldots$.


## Coordination of Movement

Consider a sequence of point $p_{0}, p_{1}, p_{2}, \ldots$ with $\left\{p_{i}, p_{i+1}\right\}$ critical.
Move $p_{0}$ by $0, p_{1}$ by $\varepsilon, p_{2}$ by $2 \varepsilon, \ldots$.


## Coordination of Movement

Consider a sequence of point $p_{0}, p_{1}, p_{2}, \ldots$ with $\left\{p_{i}, p_{i+1}\right\}$ critical.
Move $p_{0}$ by $0, p_{1}$ by $\varepsilon, p_{2}$ by $2 \varepsilon, \ldots$.

## Problems:


(Event 2) A non-half-integral $p \in S$ becomes half-integral.
(Event 3) A non-pivot point $r \in P(G)$ becomes a pivot.

## Coordination of Movement

Consider a sequence of point $p_{0}, p_{1}, p_{2}, \ldots$ with $\left\{p_{i}, p_{i+1}\right\}$ critical.
Move $p_{0}$ by $0, p_{1}$ by $\varepsilon, p_{2}$ by $2 \varepsilon, \ldots$.

## Problems:


(Event 2) A non-half-integral $p \in S$ becomes half-integral.
(Event 3) A non-pivot point $r \in P(G)$ becomes a pivot.
Spines (pushed sequences of points) start with a root (half-integral point if possible).

## Velocities

Another problem appears within our simple pushing idea:


## Velocities

Another problem appears within our simple pushing idea:


We can orchestrate this type of movement by introducing

- well-defined directions between points,
- movement signs and velocities,
- spines only starting in a defined set of roots.


## Velocities

Another problem appears within our simple pushing idea:


We can orchestrate this type of movement by introducing

- well-defined directions between points,
- movement signs and velocities,
- spines only starting in a defined set of roots.


## Lemma

The choice of such a spine does not influence the movement of a point.

## Algorithmic Implications

treewidth $\mathrm{tw}(G)$

- XP with running time $(2 L)^{\operatorname{tw}(G)} n^{\mathcal{O}(1)}$
- no $n^{o(\operatorname{tw}(G)+\sqrt{k})}$, assuming ETH
pathwidth $\mathrm{pw}(G)$, size of a feedback vertex set fvs $(G)$
- W[1]-hard even for the combined parameter $\mathrm{pw}(G)+k$
- W[1]-hard for fvs( $G$ )
treedepth $\operatorname{td}(G)$
- FPT with running time $2^{\mathcal{O}\left(\operatorname{td}(G)^{2}\right)} n^{\mathcal{O}(1)}$
- no $2^{o\left(\operatorname{td}(G)^{2}\right)}$ algorithm, assuming ETH
natural parameter $k$ :
- FPT if $\delta \leq 2$
- W[1]-hard if $\delta>2$


## Dense Graphs - Cliques


(a) $\delta \in\left(\frac{3}{2}, 2\right]: F(S)$ is a matching.

(b) $\delta \in\left(1, \frac{3}{2}\right]: F(S)$ is a star.

## Neighborhood Diversity

[Hartmann, L.; 2022+] Structural parameterization of dense graphs
Parameter including large cliques:
Neighborhood diversity $\operatorname{nd}(G)$


Illustration from [Ganian; SOFSEM 2012]

## Canonical Form



## Algorithmic Techniques

(1) Guess structure of canonical form and position of additional points

## Algorithmic Techniques

(1) Guess structure of canonical form and position of additional points
(2) Linear programming to compute existence of feasible edge positions

## Algorithmic Techniques

(1) Guess structure of canonical form and position of additional points
(2) Linear programming to compute existence of feasible edge positions

- Maximizing the Matchings



## Algorithmic Techniques

(1) Guess structure of canonical form and position of additional points
(2) Linear programming to compute existence of feasible edge positions
(3) Maximizing the Matchings


## Theorem

DISPERSION can be solved in time $2^{\mathcal{O}\left(\operatorname{nd}(G)^{2}\right)} n^{\mathcal{O}(1)}$.

## Thank you!

